TEXAS A&M* Engineering

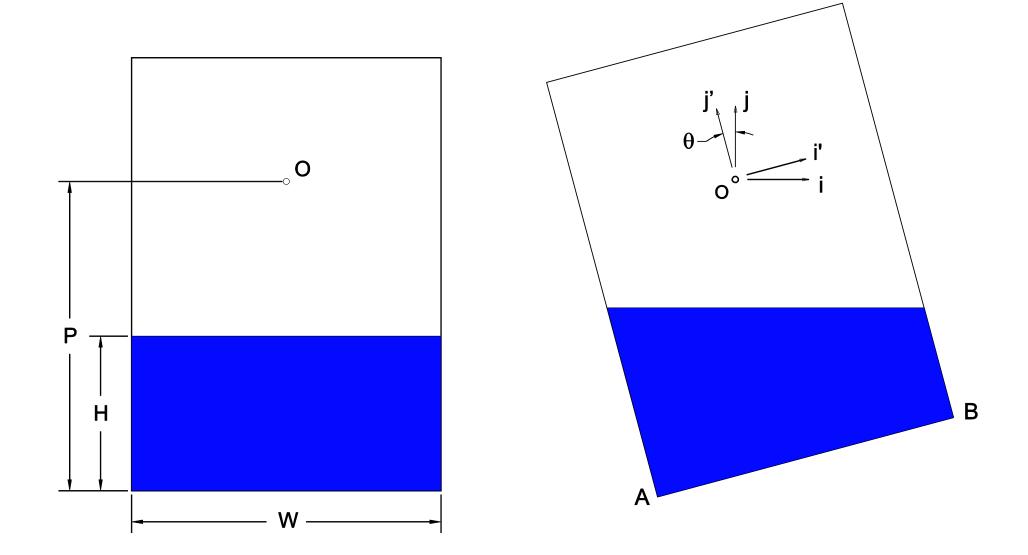
Equilibrium and Stability of Rectangular Liquid-Filled Vessels Russell Trahan & Tamás Kalmár-Nagy Department of Aerospace Engineering, Dwight Look College of Engineering



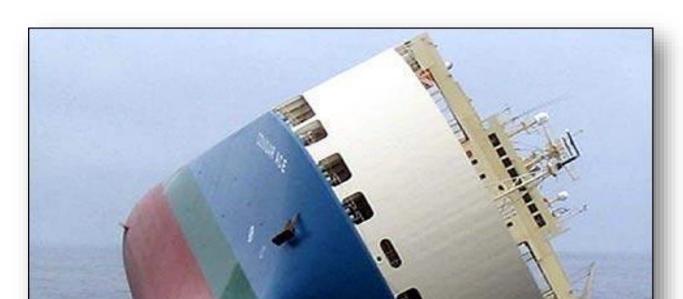




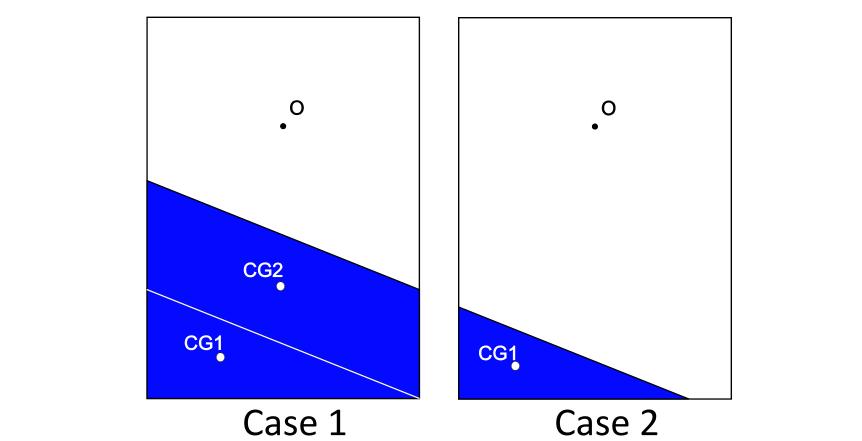
A rectangular vessel containing liquid can have several rotated equilibrium positions. The location and stability of these equilibria are based on the width of the vessel W, the height of the pivot point P, and the amount of liquid H.



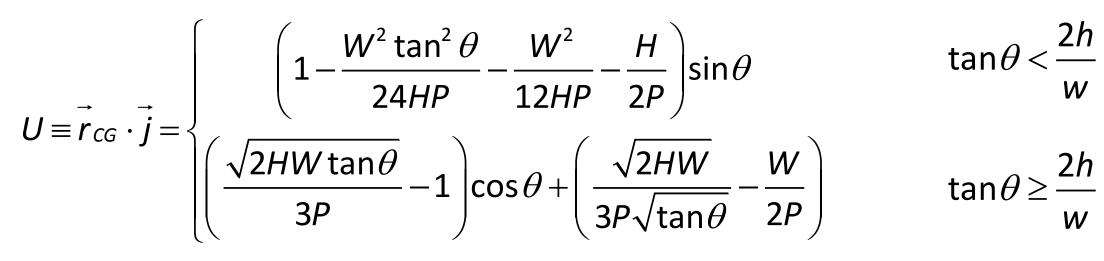
Applications include:
Marine structures
Tanker ships
Aircraft fuel systems



Define the position of the center of gravity (CG) of the liquid:

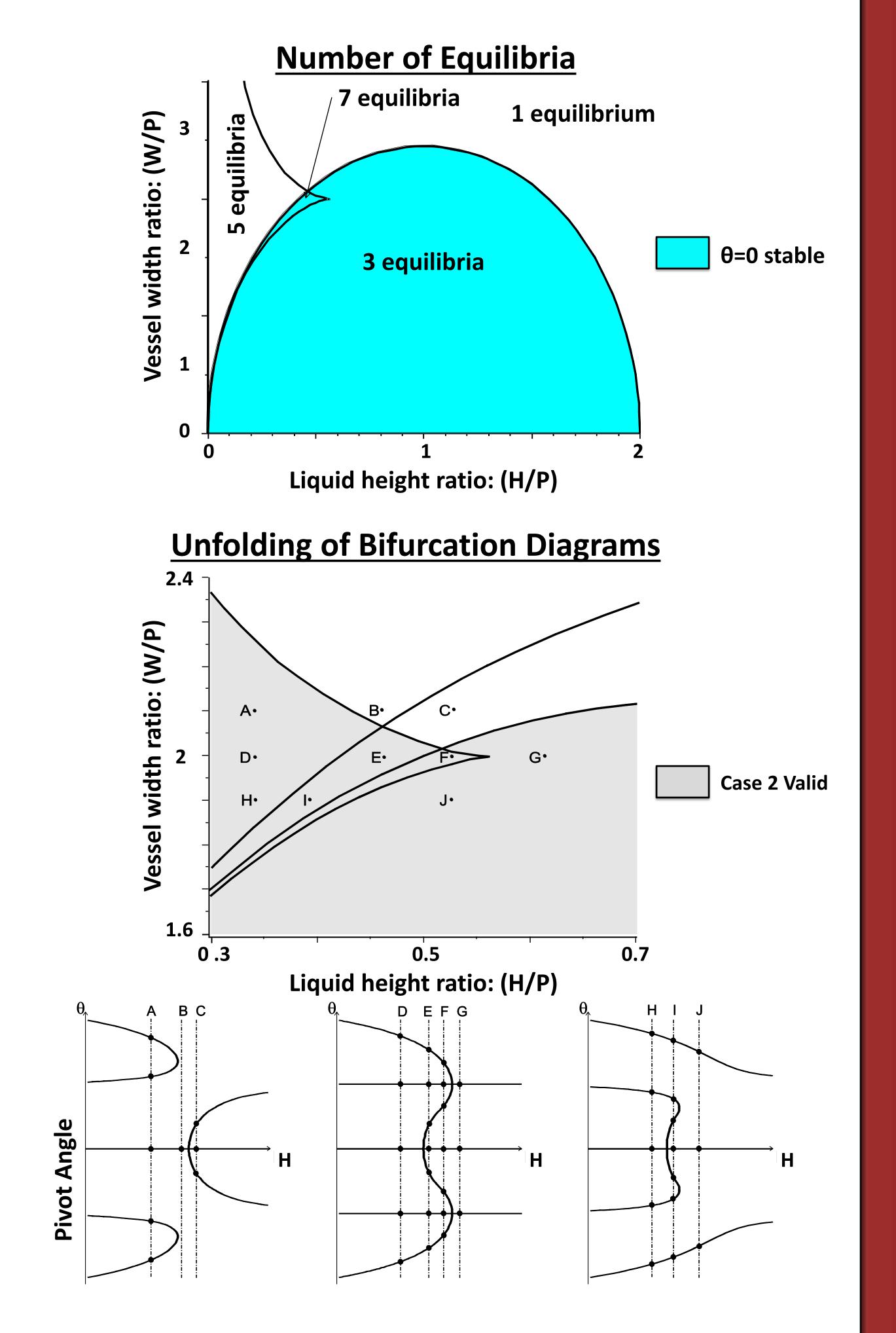


Define non-dimensional gravitational potential of the CG for both cases:



Derivative zeros correspond to equilibria: Equilibrium Positions

- The vessel can have up to seven equilibrium positions.
- For some amounts of liquid, there are no stable equilibria.
- There is a maximum width of the vessel and maximum height of water for which stable equilibria can exist.



Mobile machinery

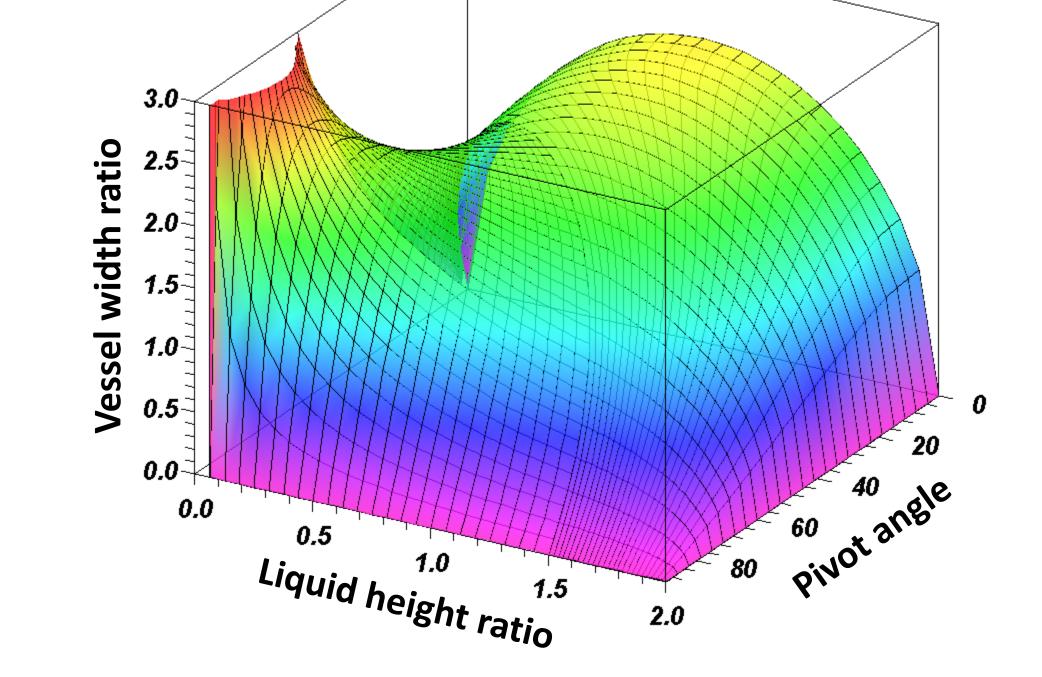


Ship listing due to shifting liquid payload

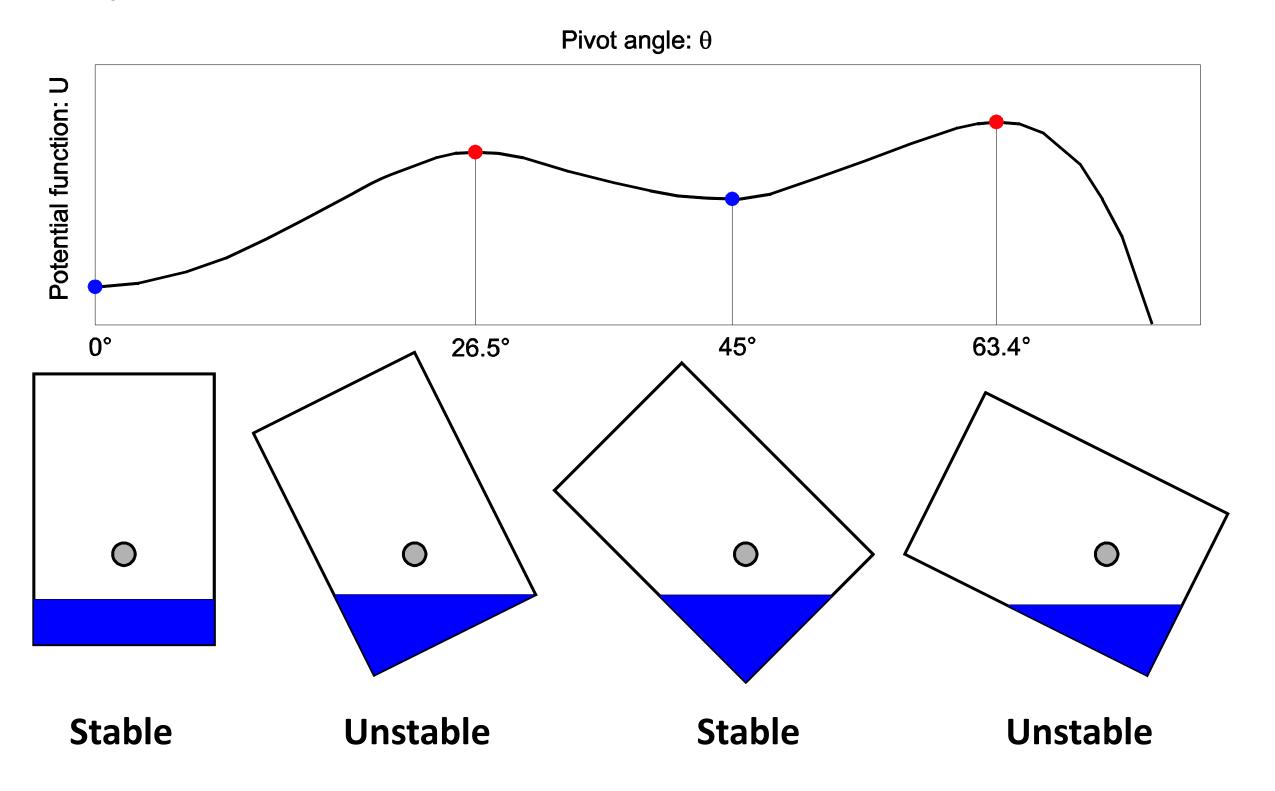
Experiment

A test "bucket" was constructed to validate the calculated results. The data collected supports the predictions.





Second derivative classifies the stability of an equilibrium:



Theoretical and Experimental Bifurcation Diagrams

The equations governing Case 1 and Case 2 equilibrium and stability have domains of validity. These restrictions define regions with various numbers of equilibria. Some regions have one equilibrium while other can have up to seven.

