

Low-cost chirp linearization for longrange ISAL imaging application

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Presented by Russell Trahan

- Hardware Outline
	- System Overview
	- Tunable Laser
	- Frequency Monitor
- Chirp duration rationale based on atmospheric turbulence
- Hardware Chirp Linearization
- Software Chirp Linearization
- Chirp Quality measured from Impulse Response

Hardware \bullet ○○○○ Chirp Duration ○○ Linearization ○○○ Chirp Quality ○○○○

- Tunable laser
- Frequency Monitor measures chirp rate
- Imaging system observes the target

Hardware ●●○○○○ Chirp Duration ○○ Linearization ○○○ Chirp Quality ○○○○

Tunable Laser

- Thorlabs TLK-1300R Fiber-Coupled Littrow external cavity laser
- 50mW
- 10dB tuning range of 130 nm, 1310 nm center wavelength
- Electric servo tuner replaced with Thorlabs DRV181 PZT

Hardware ●●●○○○ Chirp Duration ○○ Linearization ○○○ Chirp Quality ○○○○

Frequency Monitor California Institute of Technology

- Fiber Mach-Zehnder interferometer with 30m path length difference
- AOM frequency difference 400kHz
- Beat frequency measured by photodiode: $\Delta \tilde{f} = \frac{d \tilde{f}}{dt}$ dt x_D $\frac{CD}{c} + \Delta f_{AOM}$
- Batch 1000 voltage measurements, FFT, identify frequency of peak as $\varDelta \tilde{f}$, solve for $\frac{d\tilde{f}}{dt}$

Hardware ●●●●○○ Chirp Duration ○○ Linearization ○○○ Chirp Quality ○○○○

Imaging System

- AOM frequency difference 900kHz
- 90% laser power illuminated the target
- 10% laser power acts as local oscillator for heterodyne detection
- Range-to-target varies from 2 meters to 400 meters for different tests

Hardware ●●●●●○ Chirp Duration ○○ Linearization ○○○ Chirp Quality ○○○○

Long Range Testbed **Jet Propulsion Laboratory** California Institute of Technology

- 400 meters from transmitter/receiver to mirror target
- Observed effects of atmospheric turbulence using non-chirped signal
- Used unwrapping of phase of return signal to determine limit on chirp duration

Hardware ●●●●●● Chirp Duration ○○ Linearization ○○○ Chirp Quality ○○○○

Tabletop Testbed

- 2 meters from transmitter/receiver to target
- ISAL imaging demonstrations
- Operates at high or low CNRs
- Operates with or without synthesized atmospheric turbulence

Hardware ●●●●●● Chirp Duration ●○ Linearization ○○○ Chirp Quality ○○○○

50m Atmosphere Characterization

Hardware ●●●●●● Chirp Duration ●● Linearization ○○○ Chirp Quality ○○○○

Phase Unwrapping **Jet Propulsion Laboratory** California Institute of Technology

- Atmospheric turbulence will cause the phase of the return signal to drift
- To focus an image from the ISAL system, the phase must be connected between pulses
- Phase drift between pulses must be less than $\pi/2$
- Phase of non-chirped signal unwrapped.
	- Allan deviation of phase computed for inter-chirp drift
	- Standard Deviation of pulses' phase (sub std) computed for intra-chirp drift
- Chirp rate between 20 and 40 milliseconds

Hardware ●●●●●● Chirp Duration ●● Linearization ●○○ Chirp Quality ○○○○

Uncompensated Chirp California Institute of Technology

- Laser uses a PZT to move a grating to tune the laser
- Control input is a triangle wave which would ideally give a square wave for chirp rate
- Frequency monitor gives the chirp rate
- PZT is not closed loop and has finite frequency response
- Ringing is observed when PZT changes directions
- Constant control rate does not give constant tuning rate

Hardware ●●●●●● Chirp Duration ●● Linearization ●●○ Chirp Quality ○○○○

Iterative Compensation California Institute of Technology

- Control is open loop, but loop can be manually closed by iterating on the control input
- Shift response to compensate for time delay in PZT controller
- Compute error between control and response
- Proportional gain: 0.5
- Low-pass filter (moving window average) smooths the control input to remove ringing from feed-back signal when PZT reverses travel direction
- Several iterations performed

Hardware ●●●●●● Chirp Duration ●● Linearization ●●● Chirp Quality ○○○○

Post-processing

- The chirp rate can be manipulated by distorting time
- Voltage history from the receiver photodiode can be resampled in time to compensate for fluctuations in the chirp rate
- The noisy chirp rate $\frac{d\tilde{f}}{dt}$ is measured by the frequency monitor
- The phase progression is related to the passage of time: $\varphi =$ $d\tilde{f}$ dt \mathcal{X} $\frac{x}{c}$ + Δf_{AOM}) (\tilde{t}_f – t_0
- Replace the noisy chirp rate with a constant and introduce pseudo time: $d\tilde{f}$ dt \mathcal{X} $(\frac{x}{c} + \Delta f_{AOM})(\tilde{t}_f - t_0) =$ $d\bar{f}$. dt \mathcal{X} $\frac{x}{c}$ + Δf_{AOM}) (\bar{t}_f – t_0
- Take photodiode voltage history V_i and sample at fractional index $i' = i + \sum_{j=0}^{i}$ $d\widetilde{f}(t_j)$ $\frac{(f)}{dt}$ $d\overline{f}$ dt \mathcal{X} $\mathcal{C}_{0}^{(n)}$ $\overline{d\overline{f}}$ dt \mathcal{X} $\frac{x}{c}$ + Δf_{AOM}

Hardware ●●●●●● Chirp Duration ●● Linearization ●●● Chirp Quality ●○○○

Before Resampling After Resampling

Hardware ●●●●●● Chirp Duration ●● Linearization ●●● Chirp Quality ●●○○

Frequency Monitor PSD

Before Resampling After Resampling

Down-Chirp, Return Frequency, MHz

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Impulse Response (IPR) California Institute of Technology

- Shiny metal ball as target of ISAL transceiver (nearly perfect point target)
- Resample voltage history to linearize chirp
- Averaged PSD of ~200 linearized chirps
- Main lobe closely matches the theoretical IPR function. Difference indicates loss of 0.04mm of range resolution out of 2mm total resolution.

Hardware ●●●●●● Chirp Duration ●● Linearization ●●● Chirp Quality ●●●●

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Example Imaging Result

Hardware ●●●●●● Chirp Duration ●● Linearization ●●● Chirp Quality ●●●●

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